

# Traceability in the Model-based Design of Cyber-Physical Systems

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# Motivation

- Today's products design are getting more and more complex
- Different engineering disciplines need to work together
- Frequent changes in design requirements
  
- The different roles in the engineering process are using highly specialized tools
  - Different vendors
  - Open source projects
  - In-house development



# Motivation

- **Current state of the art**
  - No whole-life-cycle tool support
  - Weak or no integration between tools
  - Minimal or no traceability between artifacts
- **Challenges for product design tools**
  - Difficult to manage change and variability of design
  - Difficult to link designs to other lifecycle artifacts
  - Difficult to trace and analyze the impact of design changes



# Traceability

- Creation and the use of links (or connections)



- Makes it possible to ensure that the requirements are met
- Enables analysis on models such as coverage, impact analysis
- Facilitates documentation of system development (model evolution documentation)



# Challenges of Traceability Management

- Development by distributed teams
- Artifacts and links undergo constant change
- Involve multiple stakeholders with different background
- Trace links often manually created or not created at all
  
- Existing traceability approaches are either limited to
  - A specific domain and problem, or
  - Lack proper specification of traceability link semantics



# Key Contribution

- Developing an OSLC tool-chain data integration architecture to link artifacts from different lifecycle tools
- Goal
  - Identify integration scenario for tool integration
  - Develop traceability information model (TIM)
  - Develop a prototype to support that integration scenario (Proof of Concept)
  - Test the prototype with cross domain lifecycle tools

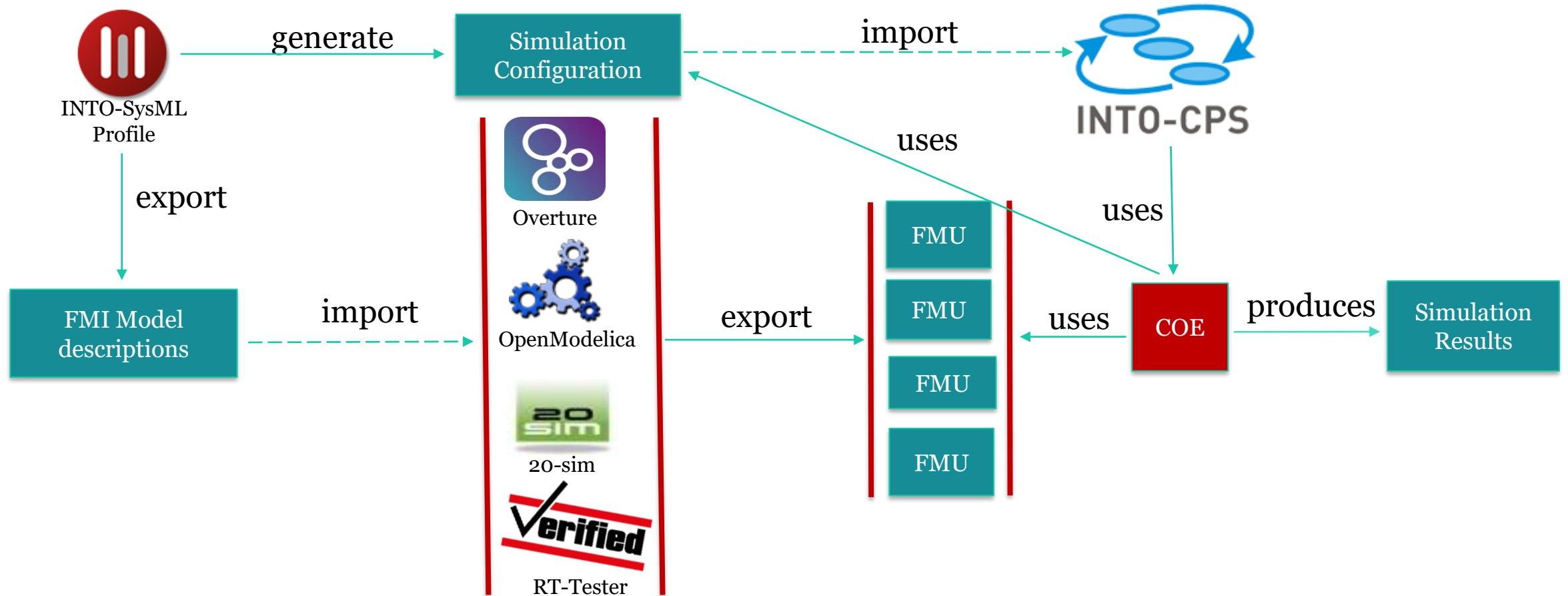


# Open Services for Lifecycle Collaboration (OSLC)

- Lifecycle integration based on Web standards
  - Linked Data and
  - RESTful Web Services
- Minimal web-based API allowing workflow integration
- Linked Data approach
  - Built on Resource Description Framework (RDF)
  - Use URIs (Uniform Resource Identifier) as identifiers
  - Use HTTP URIs so that people can discover including links to other URIs

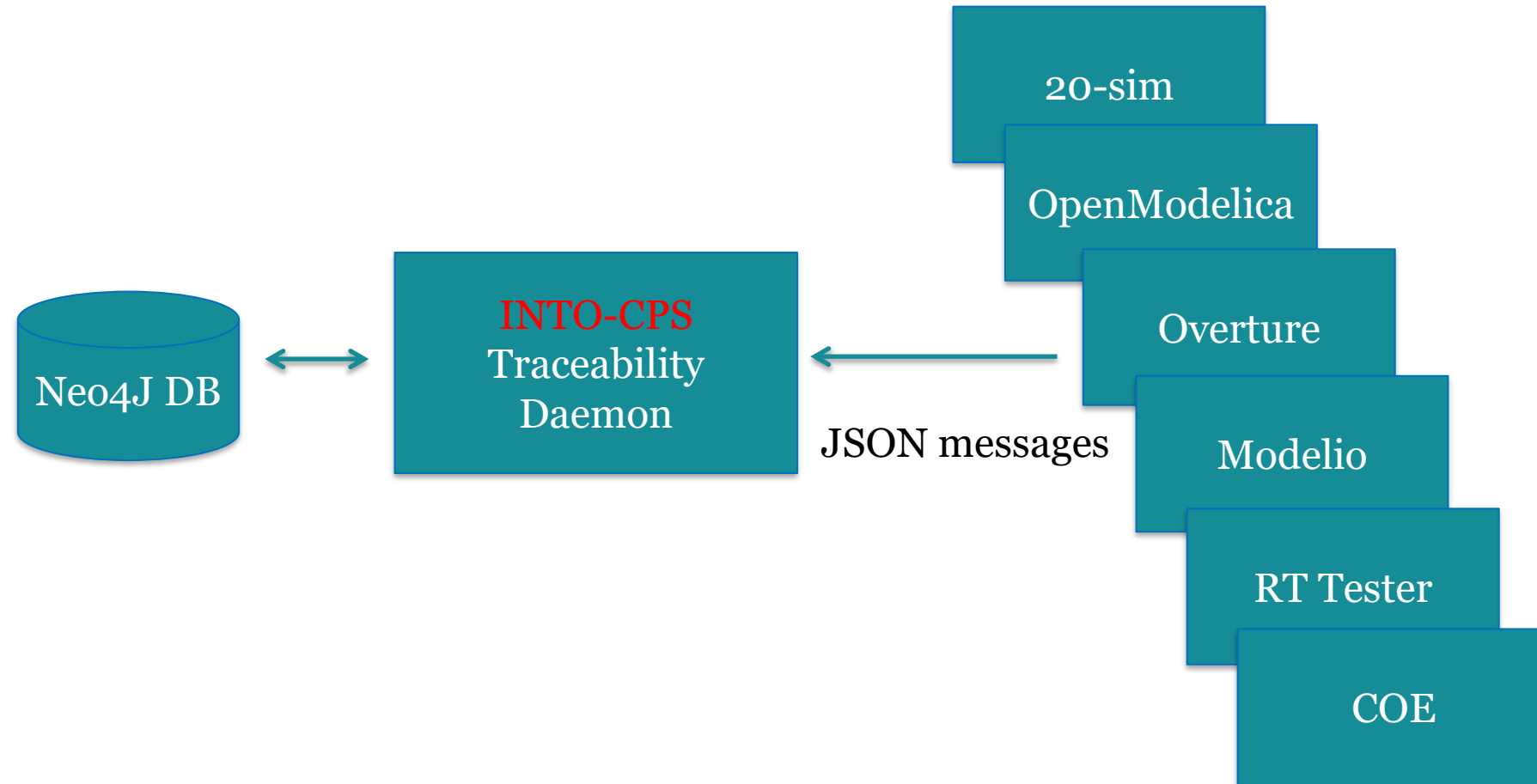


# Integration Scenario - INTO-CPS Tool Chain





# Traceability Design and Architecture



# Traceability Message Format and Ontology

- RDF triples (source, relations, target)
- Generate URIs for RDF Graphs
- JSON supported

→ “Simulation results (source) **validates** (relations) a requirement (target)”

“A requirement **satisfies** model design “

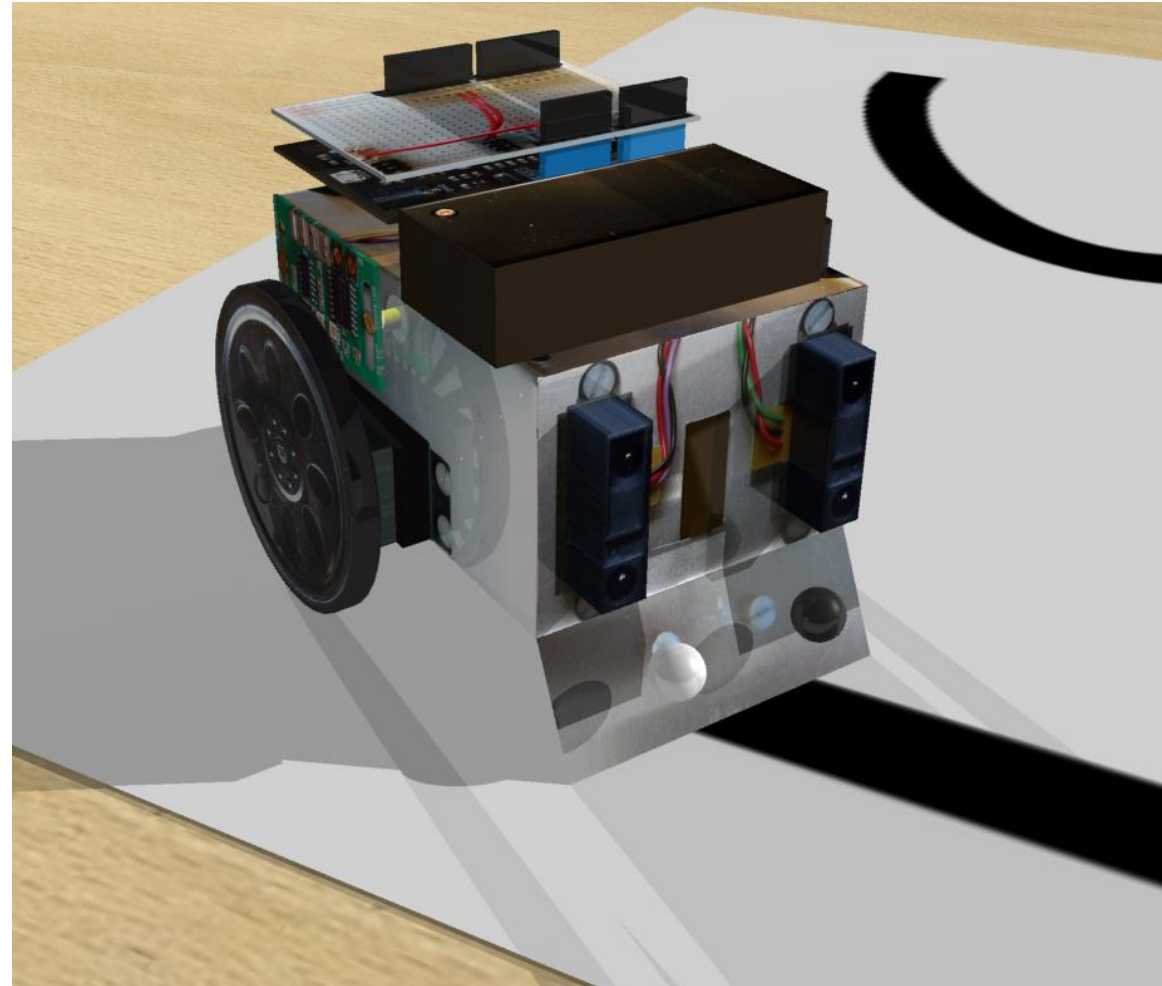
|                        |                                              |
|------------------------|----------------------------------------------|
| prov:used              | one entity used another one                  |
| prov:wasAttributedTo   | attribution of entities                      |
| prov:wasAssociatedWith | association of activities                    |
| prov:wasGeneratedBy    | one entity is generated from another         |
| prov:wasDerivedFrom    | one entity is derived from another           |
| prov:hadMember         | one entity has one or more members           |
| oslc:elaborates        | an entity that elaborates on a requirement   |
| oslc:satisfies         | an entity that satisfies a requirement       |
| oslc:verifies          | an entity that verifies an assumption        |
| into:doesNotVerify     | an entity that does not verify an assumption |
| into:violates          | an entity that violates an assumption        |



# Line Follower Robot Pilot Study

**RE1:** The robot must sense a black line

**RE2:** The robot must move faster than 5 cm/sec

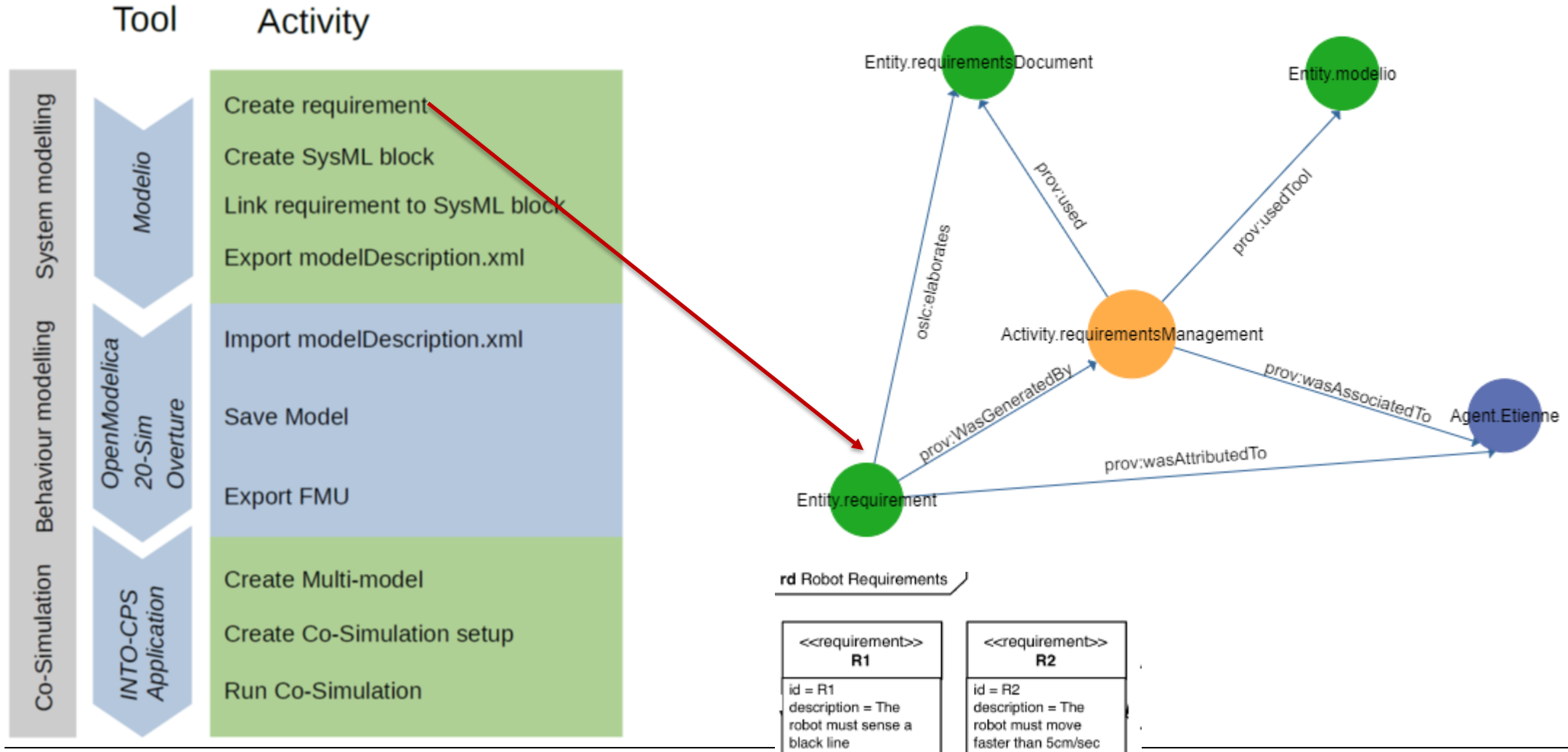


## rd Robot Requirements

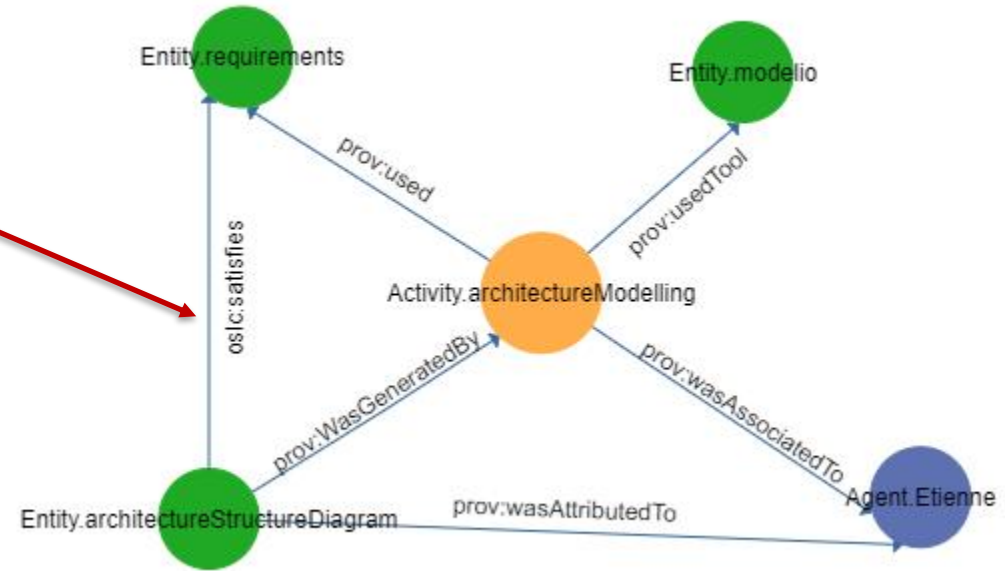
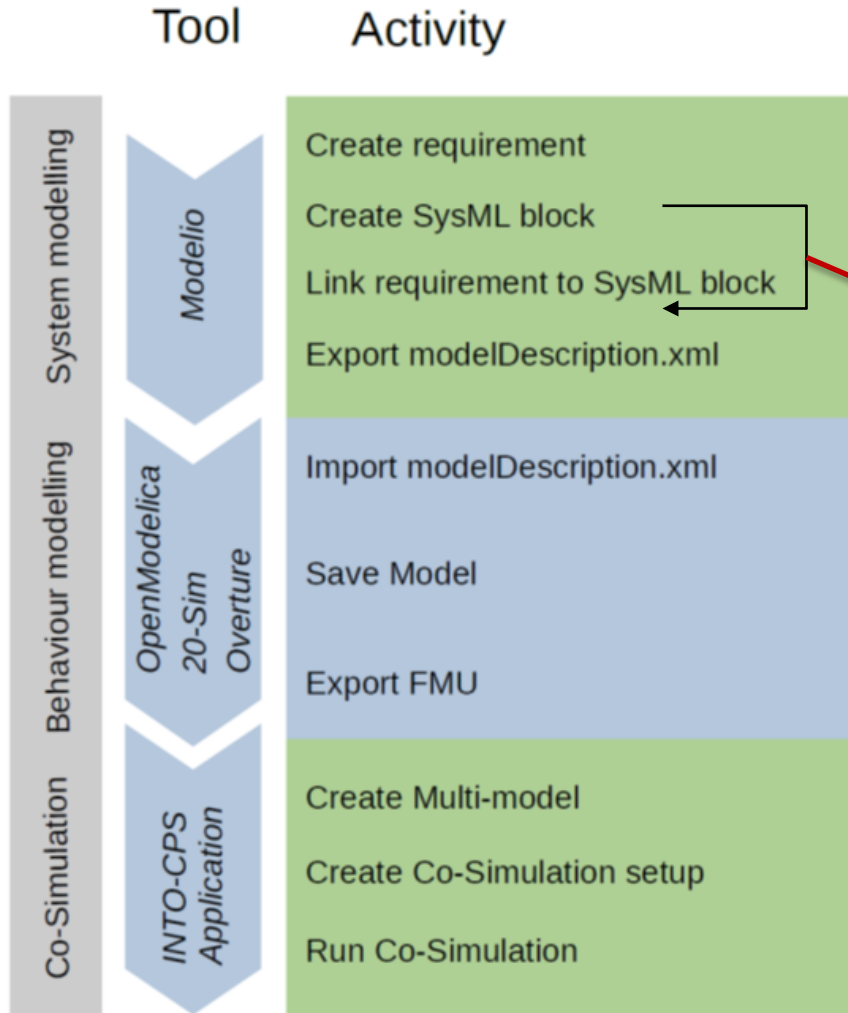
| <code>&lt;&lt;requirement&gt;&gt;</code><br>R1             | <code>&lt;&lt;requirement&gt;&gt;</code><br>R2                   |
|------------------------------------------------------------|------------------------------------------------------------------|
| id = R1<br>description = The robot must sense a black line | id = R2<br>description = The robot must move faster than 5cm/sec |



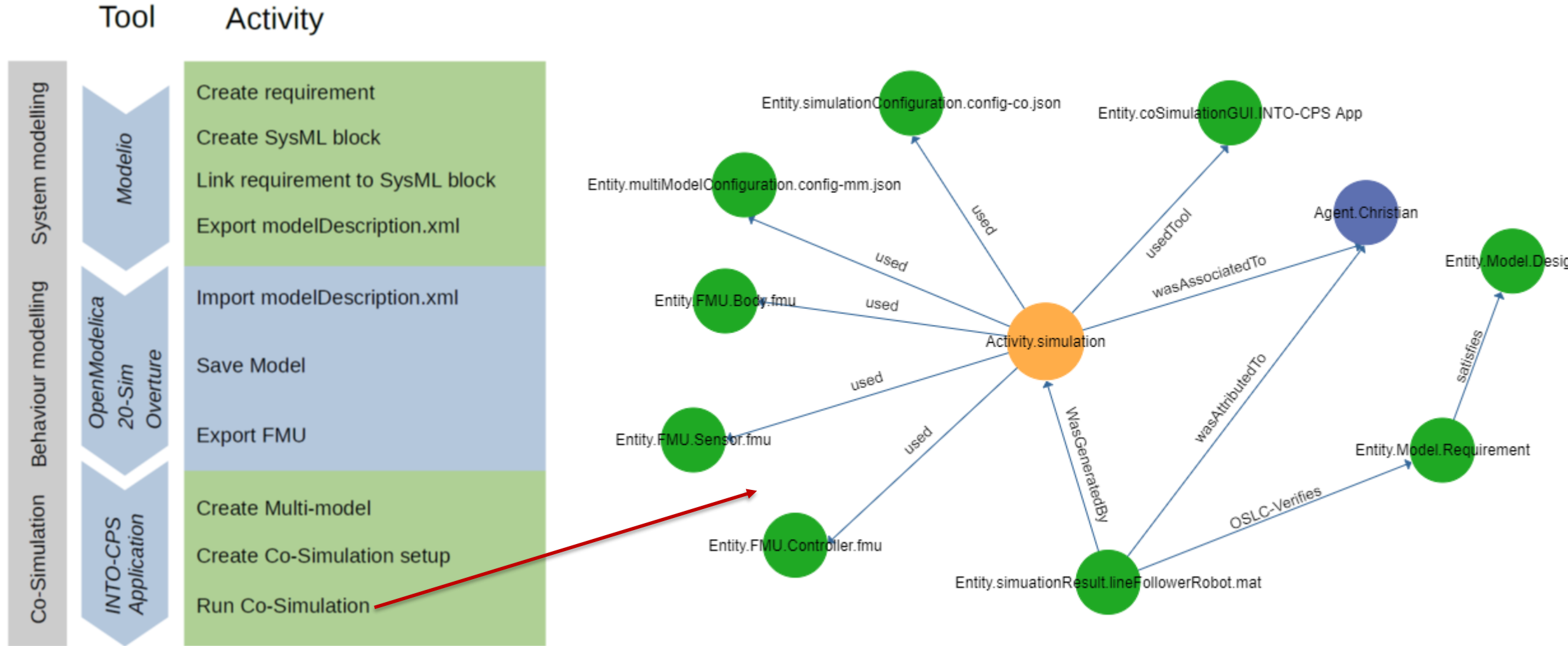
# Line Follower Robot Pilot Study - Requirements Engineering



# Line Follower Robot Pilot Study - Architectural Modeling

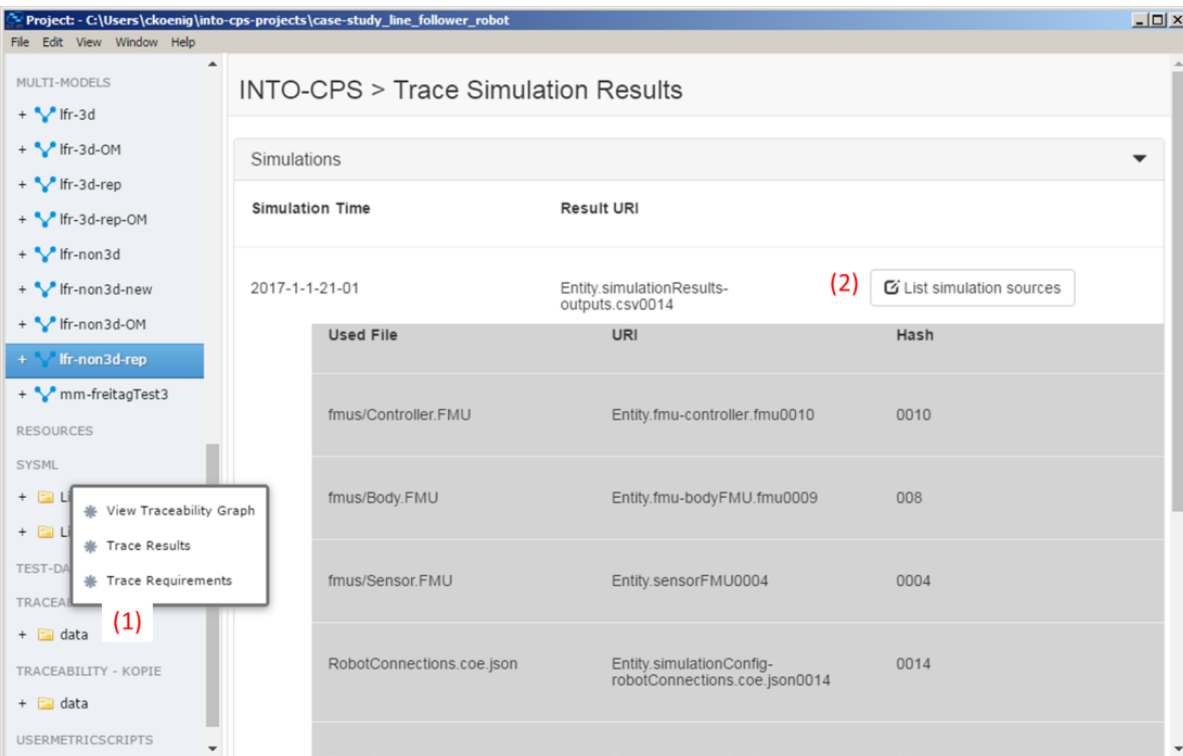
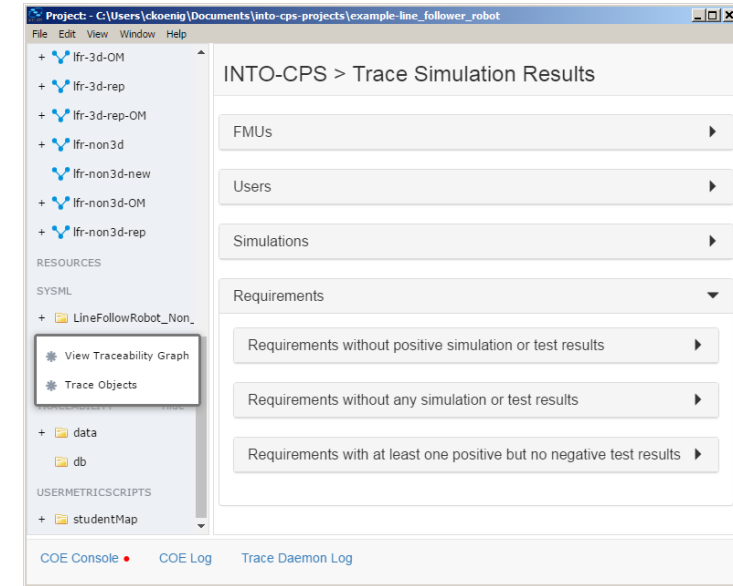


# Line Follower Robot Pilot Study - Co-simulation



# Traceability – Query User Interface

- Search simulation results → FMUs and their versions
- Search FMUs → related Requirements
- Search users → related FMUs, Requirements, simulation results



## Simulation results and files

```
match (n{type:'simulationResult'})-
  [:Trace{name:"prov:wasGeneratedBy"}]->(m)
return n.uri, m.time, m.type
```

```
match({uri:'Entity.<Result_file>')-
  [:Trace{name:"prov:wasGeneratedBy"}]->
(simulation)-
  [:Trace{name:"prov:used"}]-
(entity)
return entity.uri, entity.path, entity.hash
```



# Conclusions

- Many benefits to integrating modeling tools with other lifecycle tooling
  - Collaborative development involving multiple users
  - Traceability and data consistency across the tool-chain, cross domain queries, enhanced impact analysis
  - Difficult integration problems (e.g. creating artifacts) are handled by the native tool
- OSLC integrations have one-time investment to support core protocols
  - Adding support for specific domains (Change, Quality, etc) becomes light weight
  - Loosely coupled tool integration





# Conclusions

- Pros

- Open Technologies (Using Open Web Standards JSON, RDF, OSLC etc...)
- Reduce data integration costs, increase flexibility
- Scalability

- Cons

- Cypher query language demands expert users to manually enter queries to search the traceability database
  - Understanding of the underlying structure
- No dedicated error handling if no connection to the traceability daemon is available.



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